

Morse Theory

Goal: Investigating how functions defined on a Mfd are related to its geometric aspects

① Basics

↳ critical points

↳ degenerated Δ non-degenerated

↳ Morse Lemma

② Morse functions & the two sphere

③ Handle decomposition

- Compact surfaces

- Compact Mfids

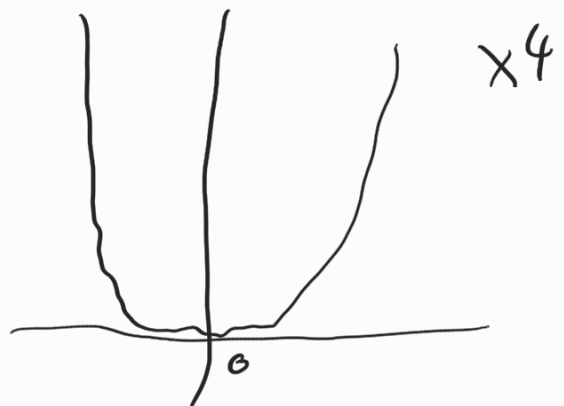
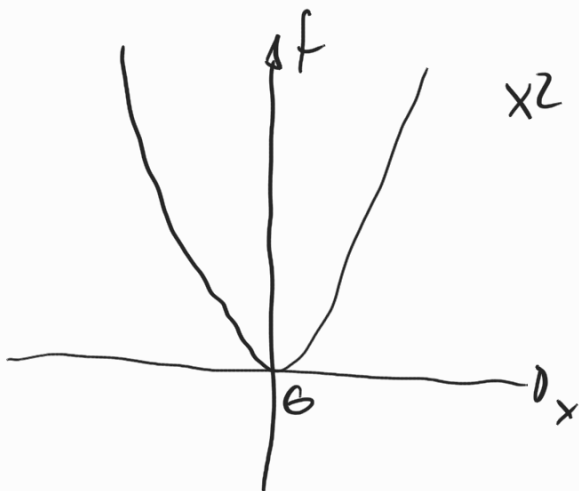
Def. 1.1

Let f be a real valued function.

A point $x_0 \in \mathbb{R}$ w/ $f'(x_0) = 0$ is called a critical point.

x_0 non-deg. if $f''(x_0) \neq 0$

x_0 degenerated if $f''(x_0) = 0$



Under part:

- non-deg. Critical points are stable
- deg. critical points are unstable

Def. 1.2 The gradient ∇f of a function is the vector field on the domain of f that takes the values $(\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n})$ at each point. Denote the VF by ∇f and the value at p as $\nabla f|_p = \nabla f(p)$

Def. 1.3

A critical point of $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is a point $p \in \mathbb{R}^n$ s.t. $\nabla f(p) = 0$.

A critical value of f is a value $c \in \mathbb{R}$ s.t. $f(p) = c$.

Def. 1.4

A critical point p_0 of a smooth function f is called degenerated if $\det(H_f|_{p_0}) = 0$

J_{p_0} the Jacobian of coord. trafo

$$(y_1, \dots, y_n)^T = J_{p_0} (x_1, \dots, x_n)^T$$

$$\tilde{H}_f(p) = J_{p_0}^T H_f(p_0) J_{p_0}$$

Prop. 1.5 The property that p_0 is a degenerated / non-degenerated critical point does not depend on the choice of local coord.

Def 1.6 Given a smooth Mfld M and a smooth function $f: M \rightarrow \mathbb{R}$, we say that f is Morse if f has no degenerated critical points.

Def. 1.7 M be a smooth Mfld.

$f: M \rightarrow \mathbb{R}$ smooth and $p_0 \in M$ is a non-degenerated critical point of f .

Then the index of f at p_0 is defined to be the number of negative eigenvalues of the Hessian at p_0 .

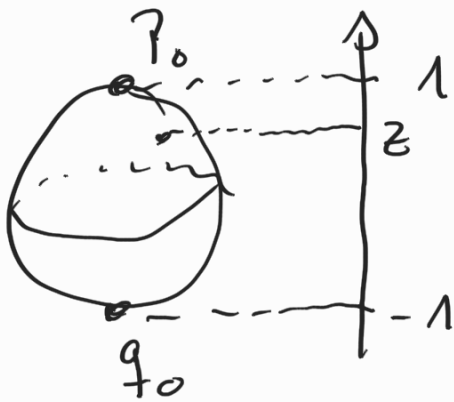
Prop 1.8 The index of f at p_0 do not depend on the choice of local coord.

Proof: Sylvester's law \rightarrow # negative eigenvalues of $H_f(p)$ is independent of the way it is diagonalized.

\Rightarrow # negative eigenvalues is invariant under local coord. transf. \square

Example:

Height function



$$f(x,y) = \pm \sqrt{1-x^2-y^2}$$

2 Critical points

$$p_0 = (0,0,1) \quad q_0 = (0,0,-1)$$

$$H_f(p_0) = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} \neq 0 \quad \text{index} = 2$$

$$H_f(q_0) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \neq 0 \quad \text{index} = 0$$

Theorem 1.9 (Existence of Morse functions)

Let M be a closed Mfd and

$f_0: M \rightarrow \mathbb{R}$ be smooth. Then there exists

a Morse function f on M that is

an arbitrarily close approx. of f_0 .

Setup • $\{U_\ell\}_{1 \leq \ell \leq h}$ finite open cover of M .

• For each U_ℓ \exists compact subset K_ℓ of U_ℓ w/ $\{K_\ell\}$ a cover of M by compact sets.

\Rightarrow idea: inductively define function f_ℓ on M s.t. f_ℓ is Morse on

$\bigcup_{j=1}^{\ell} K_j =: C_\ell$. When $\ell=h$ we have

f_h Morse on $C_h = M$.

hypothesis: $f_{\ell-1}: M \rightarrow \mathbb{R}$ Morse on $C_{\ell-1}$

\Rightarrow exists f_ℓ Morse on $C_{\ell-1} \cup K_\ell$

Do this Lemma which states that if

$\{x_{n-1}, x_n\}$ are local coord. on U_ℓ , then exists a real number $\{a_i\}$ s.t.

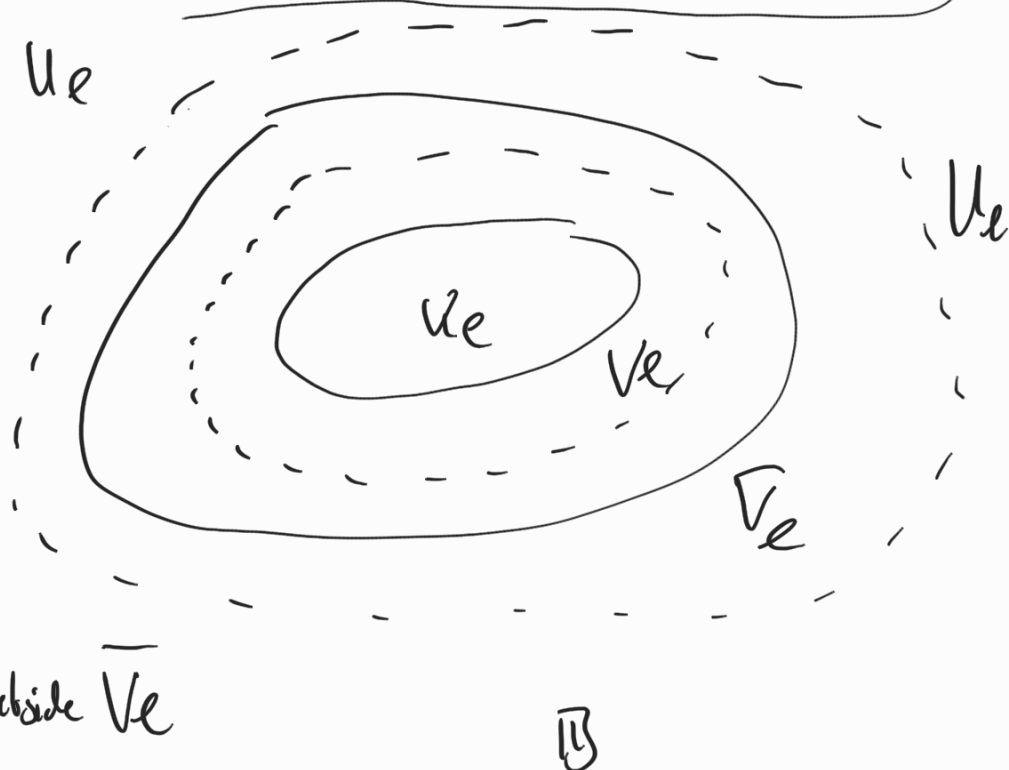
$$f_{e-1}(x_1, \dots, x_n) = (a_1 x_1^2 + a_2 x_2^2 + \dots + a_n x_n^2)$$

is Morse on U_e

$$h_e: U_e \rightarrow [0, 1]$$

being 1 on
open $V_e \subset U_e$

h_e is 0 outside \bar{V}_e



Theorem 1.10 (Morse Lemma)

Let f be a Morse function on a smooth manifold M and let p_0 be a critical point of f .

Then there exist local coord. $\{x_1, \dots, x_n\}$ on a neighborhood U of p_0 st. on U f

has the form:

$$f(x_1, \dots, x_n) = -x_1^2 - x_2^2 - \dots - x_k^2 + x_{k+1}^2 + \dots + x_n^2$$

where k is the index of f at p_0 .

p corresponds to the origin of this coord. system.

Lemma 1.11

$f: \mathbb{R}^n \rightarrow \mathbb{R}$ be smooth on a convex neighborhood $U \subset \mathbb{R}^n$ containing the origin and suppose $f(0, \dots, 0) = 0$.

Then there ex. smooth functions $\{g_i\}_{1 \leq i \leq n}$ defined on U st.

$$f = \sum_{i=1}^n x_i g_i$$

$$\text{w/ } g_i(0, \dots, 0) = \frac{\partial f}{\partial x_i}(0, \dots, 0)$$

Proof (Theorem 1.10)

$\{\gamma_1, \dots, \gamma_n\}$ being local coord. on U of p

using Lemma 1.11:

$$g_i: \mathbb{R}^n \rightarrow \mathbb{R} \quad \text{st} \quad f(\gamma_1, \dots, \gamma_n) = \sum_{i=1}^n \gamma_i g_i(\gamma_1, \dots, \gamma_n)$$

$$\text{w/ } g_i(0) = \frac{\partial f}{\partial x_i}(0)$$

\Rightarrow apply again on g_i

$$h_{ij} : \mathbb{R}^n \rightarrow \mathbb{R} \quad \text{s.t.} \quad h_{ij}(0) = \frac{\partial g_i}{\partial x_j}(0)$$

$$\Rightarrow f(x_1, \dots, x_n) = \sum_{i=1}^n \sum_{j=1}^n x_j x_i h_{ij}(x_1, \dots, x_n)$$

$$\frac{\partial^2 f}{\partial x_i \partial x_j}(p) = \begin{cases} 2h_{ii} & i=j \\ h_{ij} & i \neq j \end{cases} \quad p = (a_1, \dots, a_n)$$

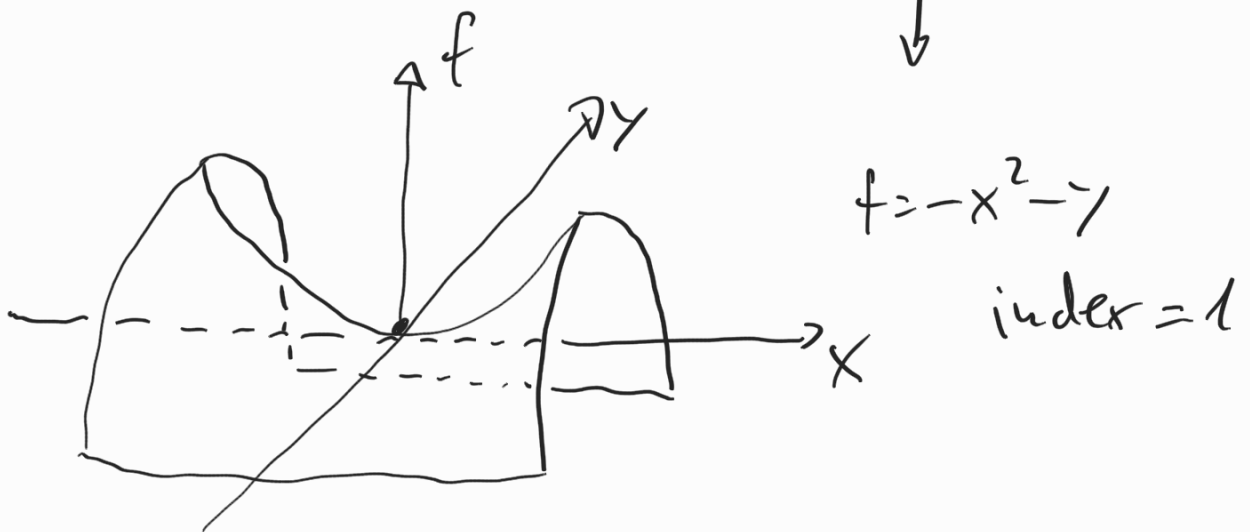
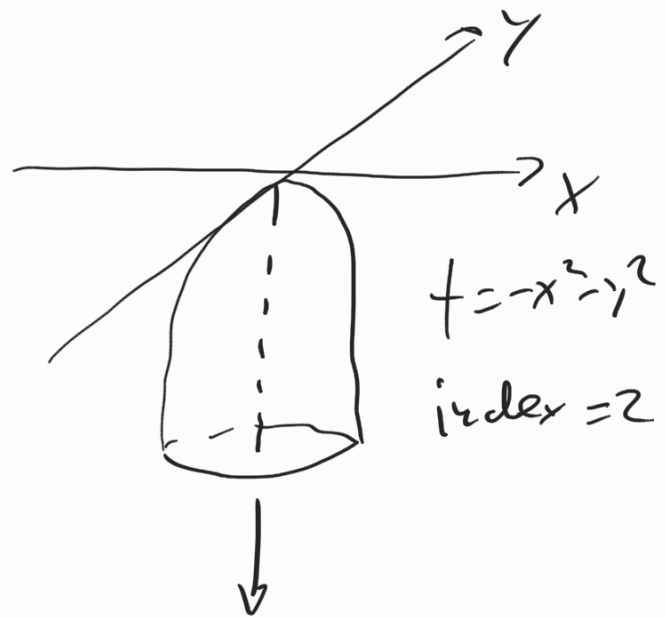
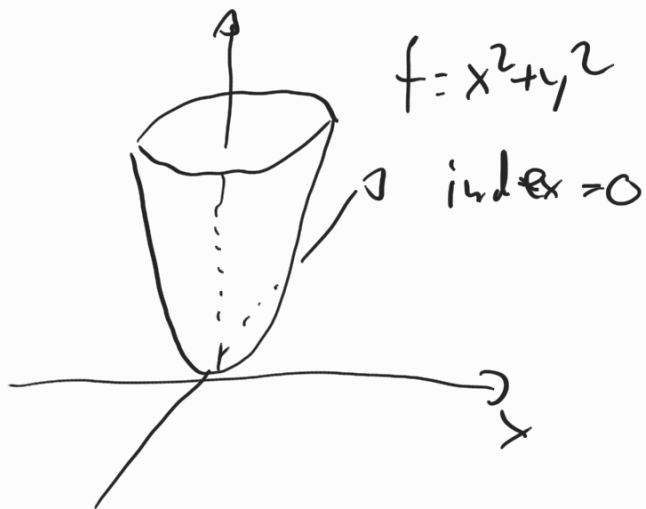
\Rightarrow Diagonalize Hessian $\rightarrow \lambda_i$ be the i th diagonal entry of $H_f(p)$

$$\Rightarrow f(\bar{x}_1, \dots, \bar{x}_n) = \sum_{i=1}^n \frac{\lambda_i}{2} \bar{x}_i^2$$

$$x_i = \delta_p(\bar{x}_i) = \text{sign}(\lambda_i) \sqrt{\frac{|\lambda_i|}{2}} \bar{x}_i$$

$$\Rightarrow f(x_1, \dots, x_n) = \text{sign}(\lambda_1) x_1^2 + \dots + \text{sign}(\lambda_n) x_n^2$$

Example 2-dim case



$\Rightarrow f$ must not have any critical point too near to any other.

Corollary 1.12 Non-deg. critical points on any Mfld can be isolated by open nbhd's

②

Theorem 2.1

Let M be a closed surface.

Suppose that there exist a Morse function $f: M \rightarrow \mathbb{R}$ w/ exactly two critical points. Then M is diffeomorphic to S^2 .

Note: Generalization to n -dim:

Reeb sphere theorem

\Rightarrow Homeomorphic to S^n

Lemma 2.2

Let $f: M \rightarrow \mathbb{R}$ be a smooth function which takes constant values on the boundary circles $C(p_0)$ & $C(q_0)$.

Assume f has no critical point M .

Then $M \cong C(q_0) \times [0, 1]$

Lemma 2.3

Let $h: \partial D_1 \rightarrow \partial D_1$ be a diffeom. Then we can extend h to a diffeom. $H: D_1 \rightarrow D_1$

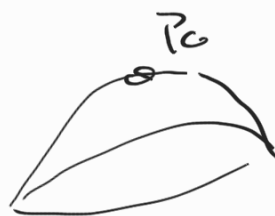
Proof

f is smooth, M compact $\Rightarrow \exists p_0$ maximum value

q_0 minimum value

Theorem 1.10 expresses f locally:

$$f = \begin{cases} -x^2 - y^2 + A, & \text{around } p_0 \\ x^2 + y^2 + a, & \text{around } q_0 \end{cases}$$



?

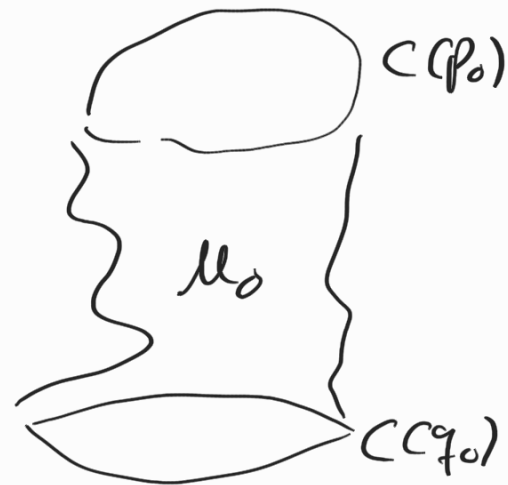


$D(p_0) := \{ \text{set of points } p \in M \text{ w/ } A - \varepsilon \leq f(p) \leq A \}$

$$= \{ (x, y) \mid x^2 + y^2 \leq \varepsilon \} \cong D^2$$

$$D(q_0) \cong D^2$$

$$M_0 := M \setminus (D(p_0) \cup D(q_0))$$



Restriction of $f: M_0 \rightarrow \mathbb{R}$

takes constant values at
 $C(p_0)$ & $C(q_0)$

\Rightarrow use Lemma 2.2. since $C(q_0) \cong S^1$

$$\Rightarrow M_0 \cong S^1 \times [0, 1]$$

$N_0 := M_0 \cup D(q_0)$ (along boundary at $D(q_0)$)

$$A_1: N_0 \rightarrow D_-$$

$$h: C(p_0) \rightarrow \partial N_0$$

$$A_1|_{\partial N_0} \circ h: C(p_0) \rightarrow \partial D_- \cong \partial D_+$$

Lemma 2.3 extends to a diffeo

$$A_2: D(p_0) \rightarrow D_+$$

⇒ gluing two diffeos together:

$$H: N_0 \cup_n D(p_0) \cong M \longrightarrow D_- \cup D_+ \cong S^2 \quad \square$$

Lemma 2.4

A Morse function $f: M \rightarrow \mathbb{R}$ defined on a closed Mfld. M has only finite number of critical points

Contradiction

infinitely many critical points

⇒ seq. of critical points:

$$\{q_n\}_{n \in \mathbb{N}} \subset M$$

compactness → conv. sub.

⇒ choose further $\{q_{n_k}\}_{k \in \mathbb{N}} \subset U$

$$q_{n_k} \rightarrow q_0, k \rightarrow \infty$$

$f(q_0)$ is also critical point. \hookrightarrow

③

$f: M \rightarrow \mathbb{R}$ Morse function. M closed & connected surface.

Define $M_t := \{p \in M \mid f(p) < t\} \subset M$

$L_t := \{p \in M \mid f(p) = t\} \subset M$

$t \leq a \Rightarrow M_t = \emptyset$

$A \leq t \Rightarrow M_t = M$



Lemma 3.1

Let $b < c$ s.t. f has no critical point in (b, c) . Then M_b & M_c are diffeomorphic

1) index of p_0 is zero

locally form: $f = x^2 + y^2 + c_0$

if c_0 minimum $\Rightarrow M_{c_0 - \varepsilon} = \emptyset$

$$\begin{aligned} M_{c_0 + \varepsilon} &= \{ p \in M \mid f(p) \leq c_0 + \varepsilon \} \\ &= \{ (x, y) \mid x^2 + y^2 \leq \varepsilon \} \cong D^2 \end{aligned}$$

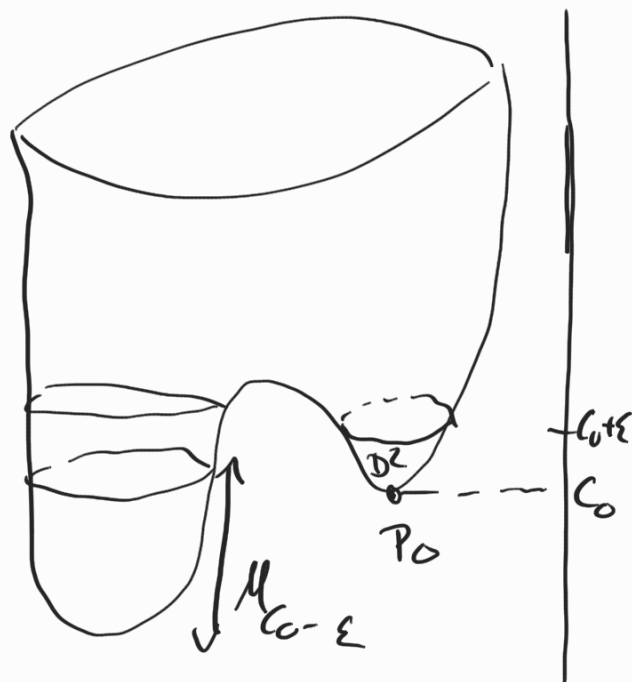
c_0 not minimum, $M_{c_0 - \varepsilon} \neq \emptyset$

$$\Rightarrow M_{c_0 + \varepsilon} \cong M_{c_0 - \varepsilon} \cup D^2$$

Crossing c_0 , a disk
pops out and set
becomes disjunct.

to disjoint union of

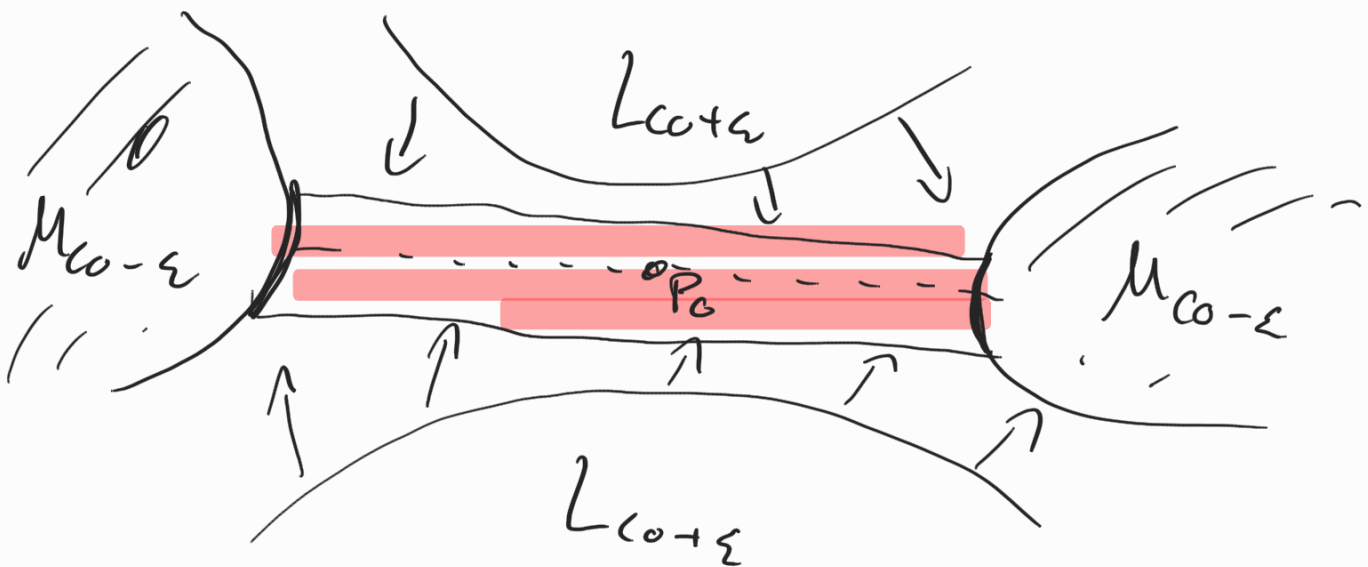
$$M_{c_0 - \varepsilon} \cup D^2$$



2) Index of p_0 is equal one.

local form : $f = -x^2 + y^2 + c_0$

red line connecting
edges $L_{c_0-\epsilon}$



Diffeom. to rectangle \Rightarrow $D_1 \times D_1$
intersecting w/ $M_{c_0-\epsilon}$ corresponds

to point $\boxed{\partial D^1 \times D^1} \Rightarrow 1\text{-handle attached}$
to $M_{C_0 - \varepsilon}$

$$M_{C_0 + \varepsilon} \simeq M_{C_0 - \varepsilon} \cup D^1 \times D^1$$

3) Index to p_0 is equal two

local form: $f = -x^2 - y^2 + c_0$

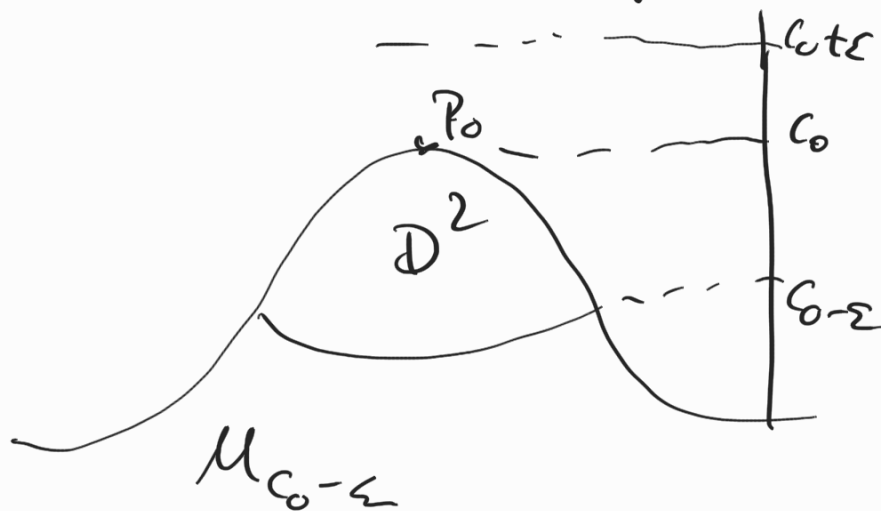
$$\Rightarrow M_{C_0 - \varepsilon} = \{ (x, y) \mid x^2 + y^2 \geq \varepsilon \}$$

$M_{C_0 - \varepsilon}$ outside a disk w/ radius $\sqrt{\varepsilon}$

Bowl D^2 capping

$M_{C_0 - \varepsilon}$ from

above $\Rightarrow 2\text{-handle}$



$$\boxed{M_{C_0 + \varepsilon} \simeq M_{C_0 - \varepsilon} \cup D^2}$$

Lemma 3.2

Let M be a smooth manifold w/ f is a Morse function on M . Then if p & q are both critical points of f s.t. $f(p) = f(q)$, then there exists a smooth manifold $M' \cong M$ s.t. $f(p) \neq f(q)$

Theorem 3.3

A closed surface M admits a Morse function $f: M \rightarrow \mathbb{R}$ and therefore M can be described as a union of finitely many 0, 1, 2 handles.

Proof:

M compact \Rightarrow th. 1.3 exists of a Morse function.

$A, B \subset \mathbb{R}$ s.t. $M_A = \{\emptyset\}$, $M_B = M$

Compactness guarantees \rightarrow finitely many critical points. Lem 2.4.

Lem 3.2 says that we can adjust M by diffeo. st $f(p_i) \neq f(p_j) \quad i \neq j$

$L := \{ \# \text{ critical points} \}$

Index each critical point st. if $i < j$

$$\Rightarrow f(p_i) < f(p_j)$$

p_1 lowest critical point & p_L highest.

$$\text{Define } a_i := \frac{f(p_i) + f(p_{i+1})}{2} \quad i \in \{1, \dots, L-1\}$$

$\Rightarrow a_i$ defined in that way st.

Sublevel sets M_{a_i} containing only critical points up to p_i .

$$\text{Set } M_0 = \{\emptyset\} \quad M_L = M$$

We see that $f^{-1}(a_i, a_{i+1})$ contains exactly one critical point.

$M_{a_{i+1}}$ is diffeomorphic to M_{a_i} attached to n -handle $(0, 1, 2)$ where is the index of a_{i+1} .

Furthermore Lemma 3.1. we have that the topology of the two sublevel sets M_{a_i} and M_b ($b > a_i$) only differ when $b > f(p_{i+1})$.

Therefore, the sequence $\{M_0, M_1, \dots, M_{L-1}, M_L\}$ is a handle decomposition of M . \square

Theorem 3.4

Let M be a compact smooth manifold.

and $f: M \rightarrow \mathbb{R}$ be a Morse function.

Suppose $a, b \in \mathbb{R}$ st $f^{-1}[a, b]$ non-empty

If $f^{-1}[a, b]$ contains one critical point
at f w/ index k , then M_b is
diffeomorphic to the union of M_a with a
 k -handle.

Theorem 3.5

There exists a handle decomposition
for every compact smooth manifold.